

ROBOTICS

IRB 930

Unleash precision and speed with high payload SCARA robots



High payload achieves more throughput by up to 10%

The IRB 930 is a 12-kg or 22-kg payload SCARA robot which provides higher payload capabilities than competing robots in its class. Capable of handling more objects in less time than other lighter payload SCARA robots, it can increase throughput by up to 10%. The high payload SCARA can also be used with sophisticated tools/grippers for delicate applications.

Outstanding performance

The OmniCore controller offers best-in-class motion control through TrueMove and QuickMove alongside built-in digital connectivity and scalable functions.

The motion control delivers an impressive cycle time of 0.38 seconds, with a repeatability deviation position of only 0.01 mm. This performance empowers the IRB 930 to enhance hourly production rates while upholding high-quality manufacturing standards.

Extraordinary downward force

IRB 930 offers a maximum downward force of 250N, providing more than double the average screw driving capacity of other robots on the market. This makes it ideally suited for not only conventional electronic applications but also green energy application areas like EV battery cells, modules, packs and solar panels. The IRB 930 is a 12-kg or 22-kg high payload SCARA robot that boosts throughput by up to 10% with classleading speed, accuracy, internal cabling, and extraordinary downward force.

IRB 930 SCARA delivers high performance across all market segments, including electronics, automotive electrical vehicles, solar, and consumer goods. IRB 930 is ideal for fast point-to-point applications, such as assembly, material handling, pick & place, and screw driving.

Omitting an external tube delivers up to 20% space saving

With all cables routed internally to remove cable interference, the IRB 930 saves up to 20% of the space typically required above the upper arm, optimizing production space and flexibility. This enables the IRB 930 to work nicely in close proximity to an inverted SCARA IRB 910INV or 6-axis robot.

Larger diameter air hose provides up to 30% faster suction

The use of a larger diameter air hose provides additional power for vacuum suction, making it possible to simultaneously handle multiple objects up to 30% faster than other robots in its class.

Increased connectivity

The option to include up to 20 I/O connectors allows more sophisticated grippers and end effectors to be used for more complex applications.

Main applications

- Assembly
- Picking/Placing
- Material Handling
- Screw driving
- Packaging
- Testing

Specification

| Robot version | IRB 930- 12/0.85 | IRB 930- 12/1.05 | IRB 930- 22/1.05 | |
|--|--|---------------------|---------------------|--|
| Reach (m) | 0.85 | 1.05 | 1.05 | |
| Payload (kg) | 12 | 12 | 22 | |
| Number of axes | 4 | | | |
| Protection | Standard IP301 | | | |
| Mounting | Floor | | | |
| Controller | OmniCore E10, C30, C90XT | | | |
| Integrated signal and power supply | Up to 20 signals ² | | | |
| Integrated air supply | 4 air on outer arm (Max. 6 Bar) ² | | | |
| Integrated ethernet | One 1000 | Base-T ethern | et port² | |
| ESD compliance IEC 61340-5-1-2016 ANSI/ESD S20.20-2021 | | | | |
| | | | | |

¹ Ballscrew area: IP20 ² Optional

Performance

| | IRB 930- 12/0.85 | IRB 930- 12/1.05 | IRB 930- 22/1.05 | |
|--|---------------------|---------------------|---------------------|--|
| 2 kg picking cycle 25 x 300 x 25 mm | 0.38 s | 0.39 s | 0.39 s | |
| Axis 3 downforce ³ | 250 N | | | |

³ Please check detail information from Product Specification

| Performance (according to ISO 9283) | | | | |
|--|---------|---------|---------|--|
| Pose repeatability, RP | 0.01 mm | 0.02 mm | 0.02 mm | |
| Path repeatability, RT | 0.05 mm | 0.05 mm | 0.04 mm | |
| Pose stabilization time within 0.1mm of the position PSt | 0.09s | 0.18s | 0.09s | |

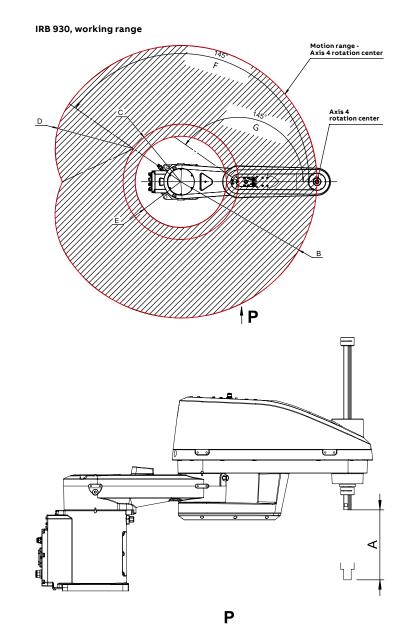
Given motion pattern with optimized setup

Physical and movement

| | IRB 930- 12/0.85 | IRB 930- 12/1.05 | IRB 930- 22/1.05 | | |
|-------------------|--------------------------------------|---------------------|---------------------|--|--|
| Robot Base | ĩ | 220 × 220 mm | | | |
| Robot weight | 64 kg | 64 kg 66 kg 66 | | | |
| Working range | | | | | |
| Axis 1 (rotation) | +145° to -145° | | | | |
| Axis 2 (rotation) | +145° to -145° | | | | |
| Axis 3 (Z) | -300 mm to 0 mm; -450 mm to 0 mm; | | | | |
| Axis 4 (rotation) | + | +400° to -400° | | | |
| Axis max. speed | | | | | |
| Axis 1 (rotation) | 410°/s | 402°/s | | | |
| Axis 2 (rotation) | 534°/s | 524°/s | | | |
| Axis 3 (A) | 2.24 m/s | | | | |
| Axis 4 (rotation) | 1702°/s | | | | |

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Working range and dimension

| | A(Axis 3) | В | с | D | E |
|-----------|-----------|---------|--------|--------|----------|
| IRB 930 | | | | | |
| 0.85_0.3 | 300 mm | 850 mm | 360 mm | 490 mm | 284.1 mm |
| 0.85_0.45 | 450 mm | 850 mm | 360 mm | 490 mm | 284.1 mm |
| 1.05_0.3 | 300 mm | 1050 mm | 560 mm | 490 mm | 322.7 mm |
| 1.05_0.45 | 450 mm | 1050 mm | 560 mm | 490 mm | 322.7 mm |

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